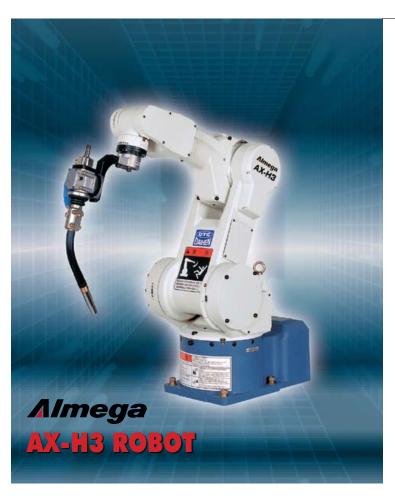


ALMEGA AX SERIES



COMPACT ARC WELDING ROBOT



Compact Design Provides Huge Space Savings

Manufacturing floor space is one of the largest considerations any company has to make when designing automated systems. Robots in particular require a large amount of space to accommodate safety measures such as fences and light curtains. The amount of space is determined by the movement range of the robot, and manufacturing areas are often consumed by providing the required safety space.

The AX-H3 arc welding robot is designed to reduce the amount of required space. The smaller, compact design of the AX-H3 provides a smaller working envelope than conventional robots, as well as a smaller required safety area. By reducing the amount of space required, you get more manufacturing space for other systems.

Robot Features & Benefits

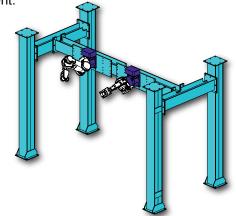
- High-speed motion improves productivity dramatically.
- Easily mounts to walls and ceilings, ideal for automobile manfacturing lines.
- Ideal for welding and cutting in both narrow places as well as large workpieces.
- Compact design reduces required manufacturing floorspace.
- Suitable for all arc welding application, including CO2, MAG, MIG, TIG, and air plasma cutting.
- Utilizes the AX-C robot controller for fast communication and improved robot movement control.
- Seamless digital interfacing with all OTC DAI-HEN D-Series products.

Increase Your Productivity

The compact design of the AX-H3 also allows for more robots to be placed in a single system. Typically, AX-H3 robotic systems range from two- to four-robot configurations. By adding more robots to a system, you can effectively reduce your cycle times and increase productivity.

Easy Robot Mounting

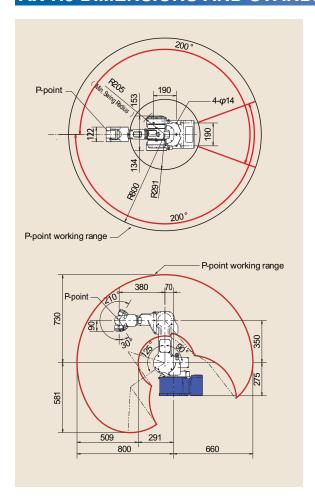
The lightweight design of the AX-H3 also allows it to easily be mounted for ceiling and wall mounted configurations, ideal for reaching positioning equipment.

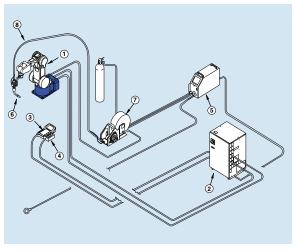


Two side-mounted AX-H3 robots

Standard Specifications

AX-H3 DIMENSIONS AND STANDARD SPECIFICATIONS





Item			Specification	
Name			AX-H3	
Structure			Vertical Articulated Type	
Number of Axes			6	
Max. Payload Capacity			6.6 lbs (3 kg)	
Positional Repeatability			±0.003" (±0.08mm) note 1	
Drive System			AC Servo Motor	
Position Feedback			Absolute Encoder	
	Arm	J1 (Rotation)	400° (±200°) note 2	
		J2 (Lower Arm)	215° (-125° ~ +90°)	
Working Range		J3 (Upper Arm)	355° (-125° ~ +230°)	
	Wrist	J4 (Swing)	360° (±180°)	
		J5 (Bending)	240° (-30° ~ +210°)	
		J6 (Twist)	720° (±360°)	
	Arm	J1 (Rotation)	3.23 rad/s (185°/s) [2.27 rad/s (130°/s) note 3]	
		J2 (Lower Arm)	2.79 rad/s (160°/s)	
Max.		J3 (Upper Arm)	4.54 rad/s (260°/s)	
Speed	Wrist	J4 (Swing)	5.93 rad/s (340°/s)	
		J5 (Bending)	5.93 rad/s (340°/s)	
		J6 (Twist)	7.33 rad/s (420°/s)	
	Allowable Movement	J4 (Swing)	6.76 N•m	
		J5 (Bending)	5.44 N•m	
Wrist		J6 (Twist)	3.92 N•m	
Load	Allowable Moment of Inertia	J4 (Swing)	0.159 kg•m ²	
		J5 (Bending)	0.103 kg•m ²	
		J6 (Twist)	0.053 kg•m ²	
Ambient Temperature			0~40° C	
Ambient Humidity			20~80% RH (No Condensation)	
Mass (Weight)			121 lbs (55 kg)	
Installation Type			Floor, Ceiling or Wall Hanging Type	
Origin Return			Not Necessary Note 4	
Paint Colo	r		Arm: White, Base: Blue	

- Notes 1. Positional repeatability calculated after operating conditions stabilize from repeated automatic operations.
 - 2. The value shown in () indicates wall-mounted conditions.
 3. The value shown in [] indicates wall-mounted conditions.
 - 4. Positional data protected by battery-backed storage inside the manipulator

TYPICAL CONFIGURATION

Item		CO2 / MAG	Pulsed MAG	
1	Manipulator	AX-H3		
2	Controller	AX-C		
3	Teach Pendant	AXTPDSON-EC08		
4	Operation Box	AXOP-0005		
5	Welding Power Source	DM350	DP400 / DP500	
6	Welding Torch	MTXC-3531 (350A, Air cooled) MTXCW-5031 (500A, Water cooled)		
7	Wire Feeder	AFF-4001		
8	Coaxial Power Cable	L-6625		

For more information on products from DAIHEN Inc., visit our website at www.daihen-usa.com, or send us e-mail at sales@daihen-usa.com.



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